Computational Astrophysics I: Introduction and basic concepts

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Numerical Integration and Differentiation

(see also Landau et al. 2007)

Computing integrals

Often integrals have to be evaluated numerically. Examples:

• measured dN(t)/dt, the rate of some events, e.g., photons per unit time interval. Task: Determine the number of photons in the first second:

$$N(1) = \int_0^1 \frac{dN(t)}{dt} dt \tag{1}$$

• radiative rates in the statistical equations for non-LTE population numbers (stellar atmospheres, photoionized nebulae)

$$R_{\ell u} = \int \frac{4\pi}{h\nu} \sigma_{\ell u}(\nu) J_{\nu} d\nu \quad \text{where (in 1d):} \ J_{\nu} = \frac{1}{2} \int_{-1}^{1} J_{\nu} d(\cos \theta)$$
(2)

Also, *analytical* integration sometimes difficult or impossible (e.g., elliptic integrals), but numerically straightforward. So, Riemann definition

$$\int_{a}^{b} f(x)dx = \lim_{h \to 0} \left[h \sum_{i=1}^{(b-a)/h} f(x_i) \right]$$
(3)

summing up areas of boxes of height f(x) and width $h \rightarrow$ numerical quadrature

$$\int_{a}^{b} f(x) dx \approx \sum_{i=1}^{N} f(x_i) w_i$$
(4)

 \rightarrow problem: find appropriate sampling $f_i \equiv f(x_i)$, with weights w_i generally: result improves with N

some hints

- remove singularities before integration
- sometimes splitting of interval is helpful, e.g.,

$$\int_{-1}^{1} f(|x|) dx = \int_{-1}^{0} f(-x) dx + \int_{0}^{1} f(x) dx$$
(5)

• or transformation/substitution

$$\int_0^1 x^{1/3} dx = \int_{y(0)=0^{1/3}}^{y(1)=1^{1/3}} y \, 3y^2 dy \qquad \left(y(x) = x^{1/3} \to dx = 3x^{2/3} dy = 3y^2 dy\right) \tag{6}$$

The Trapezoid rule

- uses values f(x) at evenly spaced x_i (i = 1, ..., N) with step size h on integration region [a, b], including endpoints
- hence, N-1 intervals of length h:

$$h = {b - a \over N - 1}$$
 $x_i = a + (i - 1)h$ (7)

• so construct trapezoid on interval *i* of width $h \rightarrow f(x)$ approximated by straight line between $(a + i \cdot h, f_i)$ and $(a + (i + 1) \cdot h, f_{i+1})$



with average height $(f_i + f_{i+1})/2$:

$$\int_{x_i}^{x_i+h} f(x) dx \simeq rac{h(f_i+f_{i+1})}{2} = rac{1}{2} h f_i + rac{1}{2} h f_{i+1}$$

i.e. Eq. (4): $\int_a^b f(x) dx \approx \sum_{i=1}^N f(x_i) w_i$ for N = 2 and $w_i = \frac{1}{2}h$ • hence for full integration region [a, b]

$$\int_{a}^{b} f(x) dx \approx \frac{h}{2} f_{1} + h f_{2} + h f_{3} + \ldots + h f_{N-1} + \frac{h}{2} f_{N}$$

i.e. $w_i = \{h/2, h, \dots, h, h/2\}$

(8)

(9)

Simpson's rule

- similar to Trapezoid rule, but with \underline{odd} number of points N
- for each interval: *f*(*x*) approximated by parabola

$$f(x) = \alpha x^2 + \beta x + \gamma \qquad (10)$$

hence area for each interval:

$$\int_{x_i}^{x_i+h} (\alpha x^2 + \beta x + \gamma) dx \qquad (11)$$

 \rightarrow like integrating the corresponding Taylor series up to *quadratic* term



• need to determine α, β, γ for f(x), so consider interval [-1, 1]

$$\int_{-1}^{1} (\alpha x^{2} + \beta x + \gamma) dx = \frac{1}{3} \alpha x^{3} + \frac{1}{2} \beta x^{2} + \gamma x \Big|_{-1}^{+1} = \frac{2\alpha}{3} + 2\gamma$$
(12)

and $f(-1) = \alpha - \beta + \gamma$, $f(0) = \gamma$, $f(1) = \alpha + \beta + \gamma$, therefore:

$$\Rightarrow \alpha = \frac{f(1) + f(-1)}{2} - f(0), \quad \beta = \frac{f(1) - f(-1)}{2}, \quad \gamma = f(0)$$
(13)

so insert Eqn. (13) into Eq. (12)

$$\int_{-1}^{1} (\alpha x^{2} + \beta x + \gamma) dx = \frac{2\alpha}{3} + 2\gamma = \frac{f(-1)}{3} + \frac{4f(0)}{3} + \frac{f(1)}{3}$$
(14)

• or more general: use two neighboring intervals to evaluate f(x) at three points for the parabola fit

$$\int_{x_{i}-h}^{x_{i}+h} f(x)dx = \int_{x_{i}-h}^{x_{i}} f(x)dx + \int_{x_{i}}^{x_{i}+h} f(x)dx$$
(15)
$$\simeq \frac{h}{3}f_{i-1} + \frac{4h}{3}f_{i} + \frac{h}{3}f_{i+1}$$
(16)

 \rightarrow pairs of intervals (hence: odd N)

• so for total integration region [a, b]

$$\int_{a}^{b} f(x)dx \approx \frac{h}{3}f_{1} + \frac{4h}{3}f_{2} + \frac{2h}{3}f_{3} + \frac{4h}{3}f_{4} + \dots \frac{2h}{3}f_{N-2} + \frac{4h}{3}f_{N-1} + \frac{h}{3}f_{N} \qquad (17)$$

with $w_i = \{\frac{h}{3}, \frac{4h}{3}, \frac{2h}{3}, \frac{4h}{3}, \dots, \frac{4h}{3}, \frac{h}{3}\} \rightarrow \text{check: } \sum_{i=1}^{N} w_i \stackrel{!}{=} (N-1)h$

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 \rightarrow numerical integration : use algorithm with least number of integration points for accurate answer

estimate error from Taylor expansion at midpoint of interval, e.g., for trapezoid rule $hf^{(2)}\frac{h^2}{12}$, \times number of subintervals N = [b - a]/h:

$$E_{\text{trap}} = \mathcal{O}\left(\frac{[b-a]^3}{12 N^2}\right) f^{(2)}, \qquad E_{\text{Simps}} = \mathcal{O}\left(\frac{[b-a]^5}{180 N^4}\right) f^{(4)}$$
(18)

$$\epsilon_{\text{trap, Simps}} \simeq \frac{E_{\text{trap, Simps}}}{f}$$
(19)

Note that for Simpson's rule 3rd derivate cancels and $E \propto 1/N^4$ \rightarrow Simpson's rule should converge faster check: find N for minimum total error (usually for $\epsilon_{ro} \approx \epsilon_{appr}$):

$$\epsilon_{\text{tot}} = \epsilon_{\text{ro}} + \epsilon_{\text{approx}} \approx \sqrt{N} \epsilon_{\text{m}} + \epsilon_{\text{trap, Simps}}$$
(20)
$$\rightarrow \epsilon_{\text{ro}} \stackrel{!}{=} \epsilon_{\text{trap, Simps}} = \frac{E_{\text{trap, Simps}}}{f}$$
(21)

Assuming some scale:

$$rac{f^{(n)}}{f} pprox 1 \qquad b-a=1 \qquad \Rightarrow \quad h=rac{1}{N}$$

(22)

Integration error III

For double precision ($\epsilon_{\rm m}\approx 10^{-15})$ and trapezoid rule:

$$\sqrt{N}\epsilon_{\rm m} \approx \frac{f^{(2)}(b-a)^3}{fN^2} = \frac{1}{N^2}$$

$$\Rightarrow N \approx \frac{1}{(\epsilon_{\rm m})^{2/5}} = \left(\frac{1}{10^{-15}}\right)^{2/5} = 10^6$$

$$\Rightarrow \epsilon_{\rm ro} \approx \sqrt{N}\epsilon_{\rm m} = 10^{-12}$$
(23)
(24)
(25)

For double precision ($\epsilon_m\approx 10^{-15})$ and Simpson's rule:

$$\sqrt{N}\epsilon_{\rm m} \approx \frac{f^{(4)}(b-a)^5}{fN^4} = \frac{1}{N^4}$$

$$\Rightarrow N \approx \frac{1}{(\epsilon_{\rm m})^{2/9}} = \left(\frac{1}{10^{-15}}\right)^{2/9} = 2154$$

$$\Rightarrow \epsilon_{\rm ro} \approx \sqrt{N}\epsilon_{\rm m} = 5 \times 10^{-14}$$
(26)
(27)
(28)

We conclude:

- Simpson's rule is better
- Simpson's rule gives errors close to ϵ_m (in general for higher order integration algorithms, e.g., RK4)
- best numerical approximation not for $N
 ightarrow \infty$, but small $N \le 1000$
- however, as $\epsilon_{\text{Simps}} \sim f^{(4)} \rightarrow \text{only for sufficiently smooth functions, i.e., for narrow peak-like functions trapezoidal rule might be more efficient$

Gaussian quadrature I

<u>So far</u>: improvement by smart choice of weights w_i , but still equally spaced points x_i (= const. h) for integral evaluation (cf. Eq. (4)),

<u>now</u>: additional freedom of choosing x_i so that *order is twice* that of previous integration formulae (so-called Newton-Cotes formulae, see \rightarrow interpolation) for *same number of nodes* $N \rightarrow \text{compute } N \times f(x_i)$.

 \rightarrow choose w_i and x_i such that integral is *exact* for

orthogonal polynomials \times specific weight function W(x)

$$\int_{a}^{b} g(x) dx = \int_{a}^{b} W(x) f(x) dx \approx \int_{a}^{b} W(x) p_{n}(x) dx = \sum_{i=1}^{N} f(x_{i}) w_{i}$$
(29)

Note that the integration of the orthogonal polynomials is on [-1; +1], hence a transformation of the variables is usually necessary, e.g., for $W(x) \equiv 1$:

$$\int_{a}^{b} f(x)dx \approx \frac{b-a}{2} \sum_{i=1}^{N} f\left(\frac{b-a}{2}x_{i} + \frac{a+b}{2}\right) w_{i}$$

$$(30)$$

Gaussian quadrature II

Example: Gauß-Chebyshev quadrature

The weight function is
$$W(x) = \frac{1}{\sqrt{1-x^2}}$$
, i.e, with $f(x) = g(x)\sqrt{1-x^2}$

$$\int_{-1}^{+1} g(x) dx = \int_{-1}^{+1} \frac{f(x)}{\sqrt{1-x^2}} dx \approx \int_{a}^{b} \frac{T_n(x)}{\sqrt{1-x^2}} dx = \sum_{i=1}^{N} w_i f(x_i) = \sum_{i=1}^{N} w_i g(x_i) \sqrt{1-x_i^2}$$
(31)

with analytic(!) $w_i = \frac{\pi}{N}$, and $x_i = \cos\left(\frac{2i-1}{2N}\pi\right)$ are the zeros of the associated Chebyshev polynomials of 1st kind $T_n(x)$, with $T_{n+1}(x) = 2xT_n(x) - T_{n-1}$, $T_0(x) = 1$, $T_1(x) = x$ and

$$\int_{-1}^{+1} T_n(x) w(x) T_m(x) dx = \delta_{nm}$$
(32)

And for the Chebyshev polynomials of 2nd kind $U_n(x)$ analogously: $W(x) = \sqrt{1 - x^2}$, $w_i = \frac{\pi}{N+1} \sin^2 \left(\frac{i}{N+1} \pi \right)$, $x_i = \cos \left(\frac{i}{N+1} \pi \right)$

Gauß-Chebyshev quadrature in C++ for some f(x) on [a; b]

```
double gaussc (double const &a, double const &b, int const &N) {
   . . .
for (i = 0; i < N; ++i) {
  x[i] = \cos(((2. * (i+1) - 1.) * M_PI) / (double(N) *2.));
  w[i] = M_PI / double(N) * (b-a) / 2. ; // transform weights [-1;1]->[a;b]
}
sum = 0.;
for (i = 0; i < N; ++i) { // transform x in f(x), but not in sqrt()
  sum += f( x[i]*(b-a)/2. + (a+b)/2. ) * w[i] * sqrt(1.-x[i]*x[i]) ;
}
return sum :
}
```

 \rightarrow note that this is maybe not optimum for some function f(x), but should be rather used for functions of the form $f(x)/\sqrt{1-x^2}$

Most often: $W(x) \equiv 1 \rightarrow \underline{\text{Gaug-Legendre quadrature}}$ with Legendre Polynomials $P_n(x)$, which are the solutions to Legendre's differential equation (a special case of the Sturm-Liouville differential equation) \rightarrow Laplace equation in 3D for spherical coordinates \rightarrow QM

$$\frac{d}{dx}\left[(1-x^2)\frac{dP_n(x)}{dx}\right] + n(n+1)P_n(x) = 0$$
(33)

$$\rightarrow P_n(x) = \frac{1}{2^n n!}\frac{d^n}{dx^n} \left(x^2 - 1\right)^n$$
(Rodrigues' formula) (34)

so, $P_0(x) = 1$, $P_1(x) = x$, $P_2(x) = \frac{1}{2}(3x^2 - 1)$, ... Then, the *n* weights (for the *n* points of the interval)

$$w_i = \frac{2}{(1 - x_i^2)[P'_n(x_i)]^2}$$
(35)

where x_i are the *n* zeros of $P_n(x)$

Gaussian quadrature V

Table: Exact values for Gauß-Legendre integration for n = 2, 3

$$\begin{array}{ccccc} n & P_n & P'_n & x_i & w_i \\ 2 & \frac{1}{2}(3x^2 - 1) & 3x & \pm \frac{1}{\sqrt{3}} & 1, 1 \\ 3 & \frac{1}{2}(5x^3 - 3x) & \frac{1}{2}(15x^2 - 3) & 0, \pm \sqrt{\frac{3}{5}} & \frac{8}{9}, \frac{5}{9}, \frac{5}{9} \end{array}$$

Alternatively, the *n* zeros of $P_n(x)$ can be computed, e.g., via Newton's method $(x_{k+1} = x_k - P(x_k)/P'(x_k))$, one may use the start approximation (i = 1, ..., n):

$$x_i \approx \cos\left(\frac{4i-1}{4n+2}\pi\right)$$
 (36)

Then the values of $P_n(x)$ and $P'_n(x)$ for Newton's method can be obtained via recursion:

$$nP_n(x) = (2n-1)xP_{n-1}(x) - (n-1)P_{n-2}(x)$$
(37)

$$\rightarrow P_n(x) = [(2n-1)xP_{n-1}(x) - (n-1)P_{n-2}(x)]/n$$
(38)

$$(x^{2}-1)P_{n}'(x) = nxP_{n}(x) - nP_{n-1}(x)$$
(39)

$$\to P'_n(x) = (nxP_n(x) - nP_{n-1}(x))/(x^2 - 1)$$
(40)

Finally, the transformation from $t \in [-1; +1] \rightarrow x \in [a; b]$ can be done via the midpoint $\frac{a+b}{2}$

$$x_{i} = t_{i} \frac{b-a}{2} + \frac{a+b}{2}$$
(41)
$$w_{i,x} = w_{i,t} \frac{b-a}{2}$$
(42)

Alternatively, other mappings are possible, allowing for integration of improper integrals with the Gauß-Legendre quadrature

interval	midpoint	$x_i(t_i)$	W _{i,x}
$[0;\infty]$	а	$arac{1+t_i}{1-t_i}$	$\frac{2a}{(1-t_i)^2}w_{i,t}$
$[-\infty;+\infty]$	scale <i>a</i>	$arac{t_i}{1-t_i^2}$	$rac{a(1+t_i^2)}{(1-t_i)^2}w_{i,t}$
$[b;+\infty]$	a+2b	$\frac{a+2b+at_i}{1-t_i}$	$\frac{2(b+a)}{(1-t_i)^2}w_{i,t}$
[0; <i>b</i>]	ab/(b+a)	$\frac{ab(1+t_i)}{b+a-(b-a)t_i}$	$\frac{2ab^2}{(b+a-(b-a)t_i)^2}w_{i,t}$

Moreover, there exist other orthogonal polynomials useful for Gauß quadrature

interval	polynomials	W(x)
[-1;1]	Legendre	1
[-1; 1]	Chebyshev 1st kind	$\frac{1}{\sqrt{1-x^2}}$
[-1; 1]	Chebyshev 2nd kind	$\sqrt{1-x^2}$
(-1; 1)	Jacobi	$(1-t)^{lpha}(1+x)^{eta}, lpha, eta > -1$
[0; $+\infty$)	Laguerre	<i>e</i> ^{-x}
[0; $+\infty$)	Generalized Laguerre	$x^{lpha}e^{-x}, lpha > -1$
$(-\infty;+\infty)$	Hermite	e^{-x^2}

Gaussian quadrature IX

In general, the Gauß quadrature is constructed from orthogonal polynomials $p_n(x)$ with

$$\int_{a}^{b} p_{n}(x) W(x) p_{n'}(x) dx = \langle p_{n} | p_{n'} \rangle = \mathcal{N}_{n} \delta_{nn'}$$
(43)

where \mathcal{N}_n is a normalization constant. If we choose the roots x_i of $p_n(x) = 0$ and

$$w_{i} = \frac{-a_{n}\mathcal{N}_{n}}{p_{n}'(x_{i})\,p_{n+1}(x_{i})} \tag{44}$$

with $i = 1, \ldots, n$, then the error in the quadrature is

$$\int_{a}^{b} g(x) dx - \sum_{i=1}^{n} f(x_i) w_i = \frac{\mathcal{N}_n}{A_n^2(2n)!} f^{(2n)}(x_0)$$
(45)

where x_0 is some value in [a, b], A_n a coefficient of the x^n term in the polynomial $p_n(x)$, $a_n = A_{n+1}/A_n$, e.g., for the Legendre polynomials $a_n = (2n+1)/(n+1)$ and $\mathcal{N}_n = 2/(2n+1)$.

Gaussian quadrature X



Numerical integration of exp(-x) on [0, 1] with different methods and number of integration points. Note that for Simpson's rule N must be odd.

Gauß-Legendre quadrature with $W(x) \equiv 1$ is superior to simple methods with fixed integration step width. Gauß-Chebyshev is not optimal, as $W(x) = \frac{1}{\sqrt{1-x^2}}$

Romberg integration I

Ideally: choose required accuracy $\epsilon \to \text{know } n$ for Gaussian quadrature (e.g, from Eq. (45)). Unfortunately, usually impossible. Therefore: increase n until ϵ small enough, recalculate all $f(x_i)$ for new degree $n \to \text{disadvantage of Gaussian quadrature}$

Idea: trapezoid rule with subsequent calls with increasing n to refine until precision ϵ reached:

```
void trap (double const &a, double const &b, double &s, int const &n)
  . . .
if (n == 1) = 0.5 * (b-a) * (f(a)+f(b));
else {
 it = pow(2, (n-2));
 delx = (b-a) / double(it) ;
x = a + 0.5 * delx;
 sum = 0.;
for (int j=1 ; j <= it ; ++j) {
  sum += f(x); x += delx; }
 s = 0.5 * (s + (b-a) * sum / double(it));
}
```

For the trapezoid rule the approximation error (starting with $\frac{1}{n^2}$ has only even powers of $\frac{1}{n}$):

$$\int_{x_1}^{x_n} f(x) dx = h \left[\frac{1}{2} f_1 + f_2 \dots f_{n-1} + \frac{1}{2} f_n \right]$$

$$- \frac{B_2 h^2}{2!} (f'_n - f'_1) - \dots - \frac{B_{2k} h^{2k}}{(2k)!} (f_n^{(2k-1)} - f_1^{(2k-1)}) - \dots$$
(46)
(47)

If compute Eq. (47) (without the error terms) for n and get s_n and once more with 2n and get s_{2n} , then leading error term in 2nd call is 1/4 of error in 1st call, hence

$$s = \frac{4}{3}s_{2n} - \frac{1}{3}s_n \tag{48}$$

cancels leading error term, $1/n^4$ remains \rightarrow recovers Simpson's rule

Romberg integration III

Often better: trapezoid rule for different N (or $h = \frac{b-a}{N}$) + extrapolation for $h \rightarrow 0$ (cf. Richardson extrapolation) \rightarrow Romberg integration



calculate I(h_k) for series h_k
extrapolate (h²_k, I(h_k)) with polynomial in h²
e.g., ∫¹₀ e^{-x}dx

Note that polynomial $(a + bh^2)$ in h^2 is plotted, although *h* is used for the trapezoid rule \rightarrow extrapolate polynomial in h^2

 \rightarrow trapezoid rule ideal: expansion in even powers of h (each refinement $\rightarrow 2$ orders accuracy) and $I(h) = h(\frac{1}{2}f(a) + \sum_{j=1}^{N-1} f(x_j) + \frac{1}{2}f(b)) \rightarrow$ recycle already calculated nodes for h/2

Sometimes numerical derivative needed, e.g., for minimization algorithms, Newton method for root finding, so

$$f' = \frac{df(x)}{dx} := \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
(49)

Problem: for $h \to 0 \to f(x+h) \approx f(x)$

 \rightarrow subtractive cancelation for numerator

& machine precision limit for denominator

often better (e.g., for large noise): analytic approximation of function (see, e.g., \rightarrow interpolation) and its derivative

Numerical differentiation II

<u>Forward difference</u> Taylor series with step size *h*

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \frac{h^3}{6}f^{(3)}(x) + \dots$$
(50)

 \rightarrow forward difference by solving Eq. (50) for f'

$$f'_{\rm fd}(x) := \frac{f(x+h) - f(x)}{h} \simeq f'(x) + \frac{h}{2}f''(x) + \dots$$
(51)

approximate function by straight line through two points, error $\sim h$, e.g, consider $f(x) = a + bx^2$

$$f'_{\rm fd}(x) pprox rac{f(x+h)-f(x)}{h} = 2bx+bh$$
 vs. exact $f'=2bx$ (52)

ightarrow only good for small $h \ll 2x$

Numerical differentiation III

<u>Central difference</u> modify Eq. (49) by stepping forward h/2 and backward h/2

$$f'_{cd} := \frac{f(x + \frac{h}{2}) - f(x - \frac{h}{2})}{h}$$
(53)

So, if we insert Taylor series for $f(x + \pm \frac{h}{2})$ in to Eq. (53)

$$f'_{cd} := \frac{\left[f(x) + \frac{h}{2}f'(x) + \frac{h^2}{8}f''(x) + \right] - \left[\dots\right]}{h} \simeq f'(x) + \frac{1}{24}h^2f^{(3)}(x) + \dots$$
(54)

 \rightarrow all terms with odd power of h cancel \rightarrow accuracy is of order h^2 if function well behaved, i.e., $f^{(3)}h^2/24 \ll f^{(2)}h/2 \rightarrow \text{error}$ for central difference method \ll forward difference method, e.g., for $f(x) = a + bx^2$

$$f'_{cd}(x) \approx \frac{f(x+\frac{h}{2}) - f(x-\frac{h}{2})}{h} = 2bx$$
 vs. exact $f' = 2bx$ (55)

Numerical differentiation IV



Numerical differentiation V

Extrapolated difference

try to make also h^2 vanish by algebraic exatrapolation

$$f'_{\mathsf{ed}}(x) \simeq \lim_{h \to 0} f'_{\mathsf{cd}} \tag{56}$$

 \rightarrow need additional information for extrapolation by central difference with step size h/2:

$$f'_{\rm cd}(x,h/2) = \frac{f(x+h/4) - f(x-h/4)}{h/2} \approx f'(x) + \frac{h^2 f^{(3)}(x)}{96} + \dots$$
(57)

We elminate linear and quadratic error term by forming

$$f'_{ed}(x) := \frac{4\frac{f(x+h/4) - f(x-h/4)}{h/2} - \frac{f(x+h/2) - f(x-h/2)}{h}}{3}$$
(58)

$$\approx f'(x) - \frac{h^4 f^{(5)}(x)}{4 \cdot 16 \cdot 120} + \dots$$
(59)

for h = 0.4 and $f^{(5)} \simeq 1 \rightarrow \text{approximation error close to } \epsilon_m$. To minimize subtractive cancelation write Eq. (58) as

$$f'_{\rm ed}(x) = \frac{1}{3h} \left(8 \left[f\left(x + \frac{h}{4}\right) - f\left(x - \frac{h}{4}\right) \right] - \left[f\left(x + \frac{h}{2}\right) - f\left(x - \frac{h}{2}\right) \right] \right)$$
(60)

Error analysis

 \rightarrow usually decreasing *h* reduces approximation error but increases roundoff error (e.g., more calculation steps needed), moreover: subtractive cancelation. Hence, difference

$$f' \approx \frac{f(x+h) - f(x)}{h} \approx \frac{\epsilon_{\rm m}}{h} \approx \epsilon_{\rm ro}$$
 (61)

and

$$\epsilon_{\text{approx}}^{\text{fd}} \approx \frac{f^{(2)}h}{2}, \qquad \epsilon_{\text{approx}}^{\text{cd}} \approx \frac{f^{(3)}h^2}{24}$$
 (62)

Therefore $\epsilon_{\rm ro} \approx \epsilon_{\rm approx}$ for

Numerical differentiation VIII

$$\frac{\epsilon_{\rm m}}{h} \approx \epsilon_{\rm approx}^{\rm fd} = \frac{f^{(2)}h}{2}, \qquad \frac{\epsilon_{\rm m}}{h} \approx \epsilon_{\rm approx}^{\rm cd} = \frac{f^{(3)}h}{24}$$
(63)
$$\Rightarrow h_{\rm fd}^2 = \frac{2\epsilon_{\rm m}}{f^{(2)}} \qquad \Rightarrow h_{\rm cd}^3 = \frac{24\epsilon_{\rm m}}{f^{(3)}}$$
(64)

for $f' \approx f^{(2)} \approx f^{(3)} \simeq 1$ (e.g., $\exp(x)$, $\cos(x)$) and double precision ($\epsilon_m \approx 10^{-15}$):

$$h_{\rm fd} \approx 4 \times 10^{-8}$$
 & $h_{\rm cd} \approx 3 \times 10^{-5}$ (65)

$$\Rightarrow \epsilon_{\rm fd} \simeq \frac{\epsilon_{\rm m}}{h_{\rm cd}} \simeq 3 \times 10^{-8}, \qquad \Rightarrow \epsilon_{\rm cd} \simeq \frac{\epsilon_{\rm m}}{h_{\rm cd}} \simeq 3 \times 10^{-11} \tag{66}$$

 \rightarrow can choose 1000× larger *h* for *central difference* \rightarrow error is 1000× smaller for *central difference*

Numerical differentiation IX

Second derivative

starting from first derivative with central difference method

$$f'(x) \simeq \frac{f(x+h/2) - f(x-h/2)}{h}$$
 (67)

the 2nd derivative $f^{(2)}(x)$ is central difference from 1st derivative

$$f^{(2)}(x) \simeq \frac{f'(x+h/2) - f'(x-h/2)}{h},$$

$$\simeq \frac{[f(x+h) - f(x)] - [f(x) - f(x-h)]}{h^2}$$

$$\simeq \frac{f(x+h) + f(x-h) - 2f(x)}{h^2}$$
(68)
(69)
(70)

 \rightarrow Eq. (69) better in terms of subtractive cancelation

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Landau, R. H., Páez, M. J., & Bordeianu, C. C., eds. 2007, Computational Physics (Wiley-VCH)