

Computational Astrophysics I: Introduction and basic concepts

Helge Todt

Astrophysics
Institute of Physics and Astronomy
University of Potsdam

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Random numbers and Monte-Carlo methods

Many physical process can be described in two pictures:

- microscopic, individual, e.g., particle-particle interactions are considered realization usually with help of → Monte-Carlo (MC) methods
- macroscopic, only the *effective coaction* is described → usually analytical equations

Example: Thermodynamics

microscopic: motion of particles, e.g., $\overline{v^2} = \frac{1}{N} \sum_{i=1}^N v_i^2$

effective theory: thermodynamics (via statistical physics) averages particle quantities, e.g., $\frac{1}{2}m\overline{v^2} = \frac{3}{2}k_B T$, so $\overline{v^2} \rightarrow T$

Monte-Carlo simulation

Computer algorithm based on a large number of repeated random experiments to obtain a representative sample of the possible configurations.

Example: Radiative transfer

- microscopic: interaction of photons with atoms/ions/molecules
 - MOCASSIN for Monte-Carlo simulation of photon propagation in gaseous nebulae
 - MCRH (Noebauer 2015) MC radiation hydrodynamics for stellar winds
 - advantage**: arbitrary geometries (e.g., torus) and density distributions (inhomogeneities) and processes; good for scattering (special non-LTE case)
 - disadvantage**: feedback on matter (often iteratively calculated) hard to implement because of MC noise
- macroscopic: **radiative transfer equation** (RTE) = effective theory, i.e. light (intensity I_ν) instead of single photons
 - Cloudy spectral synthesis code for astrophysical plasmas
 - PoWR for emergent spectra of stellar atmospheres
 - advantage**: feedback on matter (non-LTE) via iteration (boundary conditions, e.g., conservation of energy) → non-LTE population numbers
 - disadvantage**: hard to program (numerical stability); *consistent* only for some geometries, usually 1d, e.g., spherical symmetry

For MC methods we need *good* and *many* random numbers. Usual base are uniformly distributed random numbers (= same probability for every event). Humans are not a good source for random numbers:

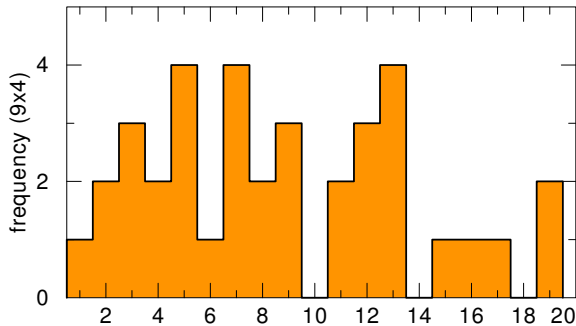


Figure: random numbers, created by colleagues → not uniformly distributed, too few

→ direct, severe consequence: don't make up your own passwords!

Other sources: rolling dices, tossing coins → low rate

most programming languages have a builtin random function, which gives **pseudo-random numbers**, e.g., in C/C++ integers (!) from $[0, \text{RAND_MAX}]$

```
#include <cstdlib>
...
int i = rand () ;
```

- output of next random number of a sequence
- restart by `srand(i)` ;

To get uniformly distributed random numbers $\in [0; 1]$:

```
r = rand()/double(RAND_MAX) ;
```

Definition

A result (a state) is random if it was not predictable.

Quality tests for random numbers:

- *uniform distribution*: random numbers should be fair
- *sequential tests*: for n -tuple repetitions (usually only for $n = 2$ und $n = 3$)
- *run tests*: for monotonically increasing/decreasing sequences, and duration of stay in a certain interval
- and more ...

→ there is no sufficient criterion for randomness tests

Non-uniform distributions

- random number generators give *uniform* (pseudo) random numbers $\in [0, \text{RAND_MAX}]$
 $\rightarrow r \in [0, 1]$ (from now on)
- we often need different distributions, e.g., normal (Gaussian) distributions or uniform distributions on an interval $x \in [a, b]$
- i.e., we need a transformation that maps r to x , so

Inverse transformation

$$x = P^{-1}(r) \quad (1)$$

Non-uniform random numbers II

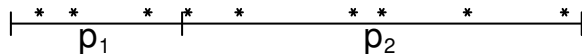
First, for the case of discrete numbers

- e.g., two events (1,2) with probabilities p_1 and p_2 , such that

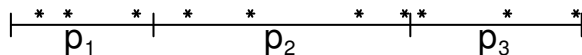
$$p_1 + p_2 = 1 \quad (2)$$

How can we choose with help of r ?

- obvious choice: for $r < p_1$ event 1, otherwise event 2



- for the case of 3 possible events with p_1, p_2, p_3 : $r < p_1 \rightarrow$ event 1, $p_1 < r < p_1 + p_2 \rightarrow$ event 2, else event 3



- in general for n events, event i is selected if for r :

$$\sum_{j=0}^{i-1} p_j \leq r \leq \sum_{j=0}^i p_j \quad \text{where } p_0 \equiv 0 \quad (3)$$

Non-uniform random numbers III

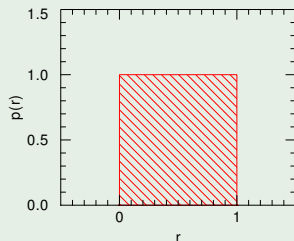
For continuous distributions:

- need the *probability density function* $p(x)$, where $p(x) \cdot dx$ is probability that x is in the interval $[x, x + dx]$
- moreover, $p(x)$ is normalized:

$$\int_{-\infty}^{+\infty} dx p(x) = 1 \quad (4)$$

Example: uniform distribution

$$p_u(r) = \begin{cases} 1, & \text{if } 0 \leq r \leq 1 \\ 0, & \text{else} \end{cases} \quad (5)$$



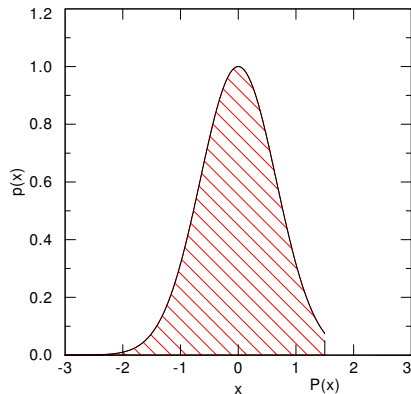
Non-uniform random numbers IV

- for the continuous case (continuum limit $i \rightarrow x$) in the Eqn. (3)

$$\sum_{j=0}^{i-1} p_j \leq r \leq \sum_{j=0}^i p_j \quad \text{where } p_0 \equiv 0$$

both sums are equal and become the integral:

$$P(x) = \int_{-\infty}^x p(x') dx' = r \quad (6)$$



This corresponds to the cumulated distribution function

$$P(x) = \int_{-\infty}^x p(x') dx' \quad (7)$$

i.e. the **probability to get a random number smaller or equal x** . Geometrically: fraction of the area left of (smaller than) x . We state:

$$P(x) = r \quad (8)$$

$$\Rightarrow x = P^{-1}(r) \quad (9)$$

i.e. exactly as r also $P(x)$ is uniformly distributed.

Therefore, the probability to find $P(x)$ in the interval $[P(x), P(x) + dP(x)]$ is $dP(x) = dr$ (Eq. 8).

The relation between $dP(x)$ and dx is obtained by derivating Eq. (7) \rightarrow Fundamental theorem of calculus:

$$\frac{dP(x)}{dx} = p(x) \quad (10)$$

for $0 \leq r \leq 1$ it is also:

$$dP(x) = p(x) dx = p_u(r) dr \quad (11)$$

I.e., because of Eq. (8) $P(x) = r \rightarrow x$ is distributed according to $p(x)$

To obtain such $p(x)$ distributed random numbers, one has to solve Eq. (9) $x = P^{-1}(r)$

Inverse transformation

- 1 Insert the required distribution $p(x)$ into:

$$r = P(x) = \int_{-\infty}^x p(x') dx' \quad (12)$$

- 2 solve for x , i.e. find

$$P^{-1}(r) = x \quad (13)$$

Not for all $p(x)$ are the corresponding conditions fulfilled (solvable integral and invertibility)

Example for inverse transformation

Let

$$p(x) = \begin{cases} a e^{-ax}, & \text{if } 0 \leq x \leq \infty \\ 0, & x < 0 \end{cases} \quad (14)$$

$$P(x) = \int_0^x a e^{-ax'} dx' = 1 - e^{-ax} = r \quad (15)$$

$$\Rightarrow x = -a^{-1} \ln(1 - r) \quad (16)$$

and $(1 - r)$ is exactly distributed as r , so:

$$x = P^{-1}(r) = -a^{-1} \ln r \quad (17)$$

The evaluation of \ln on a computer is relatively time consuming
 → inverse transformation not always the best method

Probability distributions are fundamental in, e.g., statistical mechanics and non-relativistic quantum mechanics:

- Boltzmann distribution: $p_i \propto \exp\left(-\frac{E_i}{k_B T}\right)$ for some state i
usually: **discrete** states (statistical mechanics), hence

$$p_i = \frac{N_i}{N} = \frac{\exp\left(-\frac{E_i}{k_B T}\right)}{\sum_{j=1}^m \exp\left(-\frac{E_j}{k_B T}\right)} \quad (18)$$

for N_i particles in state i and a total number of N particles with m states
but might be also **continuous**, e.g., barometric formula for molecule of mass m , height h
above ground

$$\rho(h) \propto \exp\left(-\frac{m g h}{k_B T}\right) \quad (19)$$

→ computer generated samples via **Markov Chain Monte Carlo** (MCMC), in particular
→ Metropolis algorithm (see below)

- Maxwell-Boltzmann distribution: **continuous** distribution of particle velocity in one direction (e.g., radial sightline) with $v_{\text{th}} = \sqrt{\frac{2k_{\text{B}}T}{m}}$

$$p(v_x) dv_x = \left(\frac{m}{2\pi k_{\text{B}}T}\right)^{1/2} \exp\left(-\frac{mv_x^2}{2k_{\text{B}}T}\right) dv_x = \frac{1}{v_{\text{th}}\sqrt{\pi}} \exp\left(-\frac{v_x^2}{v_{\text{th}}^2}\right) \quad (20)$$

Application: thermal Doppler broadening of spectral lines where $\Delta\nu_{\text{th}} = \nu_0 \cdot v_{\text{th}}/c$

Mean value $\langle v_x^2 \rangle = 2 \int_0^\infty v_x^2 p(v_x) dv_x = \frac{1}{2} v_{\text{th}}^2 = \frac{k_{\text{B}}T}{m} = v_{\text{s}}^2 \rightarrow$ isothermal sound speed
 \rightarrow example for a “moment” of a distribution

For 3D, absolute value, speed v : $d^3v = dv_x dv_y dv_z = v^2 dv d\Omega$ integration $\rightarrow 4\pi v^2 dv$
and $v^2 = v_x^2 + v_y^2 + v_z^2$:

$$p(v) dv = 4\pi \left(\frac{m}{2\pi k_{\text{B}}T}\right)^{3/2} v^2 \exp\left(-\frac{mv^2}{2k_{\text{B}}T}\right) dv \quad (21)$$

Hence, mean $\langle v^2 \rangle = \int_0^\infty v^2 p(v) dv = \frac{3k_{\text{B}}T}{m}$

\rightarrow compare definition of T as **measure of mean kinetic energy**

- in non-relativistic QM (1d):

the squared modulus of the wave function $|\psi(x, t)|^2$ gives probability of particle in “volume” dx around x at time $t \rightarrow p(x, t)dx = |\psi(x, t)|^2 dx$

Physical quantities (observables) have corresponding operators, e.g., momentum $p_{\text{op}} \rightarrow -i\hbar\partial/\partial x$; expectation or average value of observable A :

$$\langle A \rangle = \int \psi^*(x, t) A_{\text{op}} \psi(x, t) dx \quad (22)$$

And ψ evolves according to Schrödinger equation

$$i\hbar \frac{\partial \psi(x, t)}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi(x, t)}{\partial x^2} + V(x, t)\psi(x, t) \quad (23)$$

→ because of similarity to **diffusion equation** (with imaginary time), solutions to Eq. (23) can be found by **random walk** (see below)

- the specific intensity $I_\nu(\vec{x}, t, \vec{n}, \nu) = \frac{dE}{d\vec{A} \cdot \vec{n} d\Omega d\nu dt}$ is a 7-dim distribution function on a 4-dim spacetime manifold (\vec{x}, t) , describing unpolarized radiation. Note:

$I_\nu = n_{\text{phot}} c h \nu \geq 0$ (where n_{phot} is photons / volume / solid angle / frequency interval)

Moments of the specific intensity (radiation field) = integrals over all directions, in 1d (plane parallel, spherical symmetry) over $\mu = \cos \theta$, n -th moment: $\frac{1}{2} \int_{-1}^{+1} \mu^n I_\nu(\mu) d\mu$

n	symbol	integral	type
0.	J_ν	$= \frac{1}{2} \int_{-1}^{+1} I_\nu(\mu) d\mu$	mean intensity, energy density $E_\nu = \frac{4\pi}{c} J_\nu$, $J_\nu \geq 0$
1.	H_ν	$= \frac{1}{2} \int_{-1}^{+1} \mu I_\nu(\mu) d\mu$	(Eddington-) flux, can be neg. (e.g. "inward" flux)
2.	K_ν	$= \frac{1}{2} \int_{-1}^{+1} \mu^2 I_\nu(\mu) d\mu$	radiation pressure $K_\nu = \frac{c}{4\pi} P_\nu$
3.	N_ν	$= \frac{1}{2} \int_{-1}^{+1} \mu^3 I_\nu(\mu) d\mu$	flux-like, i.e., can be negative

→ usually: MC simulations of radiation field require large number of runs for individual photons to recover macroscopic quantities I, J , etc. correctly

Non-uniform distributions II

non-uniform distribution:

- with help of the *inversion* method we can get non-uniform random numbers from uniform random numbers \rightarrow condition: $P(x)$ **invertable**
- for the Gaussian normal distribution:

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{x^2}{2\sigma^2}\right) \quad (24)$$

$P(x)$ is not analytical representable (**error function**)

- idea: 2d-transformation where:

$$p(x, y) dx dy = \frac{1}{2\pi\sigma^2} e^{-(x^2+y^2)/2\sigma^2} dx dy \quad (25)$$

- change to polar coordinates:

$$r = \sqrt{x^2 + y^2} \quad \theta = \tan^{-1} \frac{y}{x} \quad (26)$$

- let $\rho = r^2/2$ and set $\sigma = 1$:

$$p(x, y) dx dy = p(\rho, \theta) d\rho d\theta = \frac{1}{2\pi} e^{-\rho} d\rho d\theta \quad (27)$$

- now generate random numbers ρ according to exponential distribution, so $\rho = -\ln u$ (u standard uniform distributed) and θ uniform distributed on $[0, 2\pi)$, then

$$x = \sqrt{-2 \ln u} \cos \theta \quad \text{und} \quad y = \sqrt{-2 \ln u} \sin \theta \quad (28)$$

are each according to Eq. (24) with $\sigma = 1$ and $\mu = 0$ distributed because of

$$re^{iz} = \sqrt{-\ln u} e^{i2\pi\theta} = \sqrt{-2 \ln u} [\cos(2\pi\theta) + i \sin(2\pi\theta)] \quad (29)$$

Alternative: Rejection method (see below)

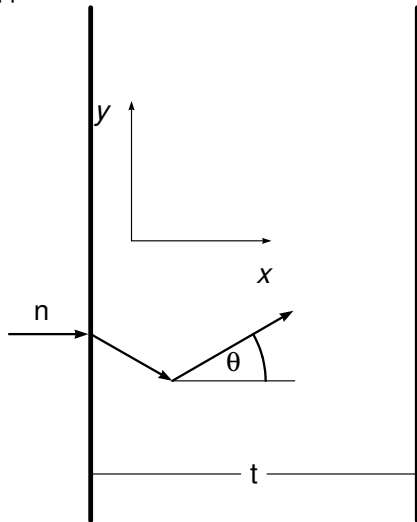
Example: Neutron transport

Neutron transport I

Application for non-uniform random numbers!

Transport of neutrons through matter – one of the first MC applications!

- consider a plate of thickness t
- plate is infinite in z and y direction, x -axis perpendicular to the plate
- at each point within the plate: probability p_c , that neutron gets absorbed (captured) and probability p_s that neutron is scattered
- after each scattering: find scattering angle θ in xy plane
- as motion in y, z direction irrelevant: azimuthal angle ϕ irrelevant



Determine scattering angle & scattering path length

1. Isotropic scattering:

$$p(\theta, \phi) d\theta d\phi = d\Omega/4\pi \quad (30)$$

$$\text{because of } d\Omega = \sin\theta d\theta d\phi : \quad (31)$$

$$p(\theta, \phi) = \frac{\sin\theta}{4\pi} \quad (32)$$

obtain $p(\theta)$ and $p(\phi)$ by integration over the complementary angle:

$$p(\theta) = \int_0^{2\pi} p(\theta, \phi) d\phi = 2\pi \frac{\sin\theta}{4\pi} = \frac{1}{2} \sin\theta \quad (33)$$

$$p(\phi) = \int_0^\pi p(\theta, \phi) d\theta = \frac{1}{4\pi} (-\cos\pi + \cos 0) = \frac{1}{2\pi} \quad (34)$$

i.e. $p(\theta, \phi) = p(\theta)p(\phi) \rightarrow$ independent variables

Neutron transport III

If random variable ϕ is wanted ($p(\phi) \equiv \text{const.}$):

$$\phi = 2\pi r \quad (35)$$

To get random θ according to Eq. (33) \rightarrow inversion method:

$$r = P(\theta) = \int_0^\theta \frac{1}{2} \sin x \, dx = -\frac{1}{2}(\cos \theta - \cos 0) \quad (36)$$

$$\cos \theta = 1 - 2r \quad (37)$$

I.e. $\cos \theta$ is uniformly distributed on $[-1; 1]$ and ϕ on $[0; 2\pi]$. Solving for θ possible, but unnecessary, as only $\cos \theta$ required for x component of the path \rightarrow

2. scattering path length:

$$x = \ell \cos \theta \quad (38)$$

where ℓ from $p(\ell) \sim e^{-\ell/\lambda}$ (see example for inversion method):

$$\ell = -\lambda \ln r \quad (39)$$

$\lambda \rightarrow$ mean free path (e.g., $\lambda = (\sigma n)^{-1}$)

Algorithm, start at $x = 0$:

- 1 determine, if neutron is scattered or captured. If captured: increment number of absorbed neutrons, go to 5 step
- 2 scattering: “dice” $\cos \theta$ and ℓ , move to x position by $\ell \cos \theta$
- 3 if $x < 0$: increment number of reflected neutrons, if $x > t$: increment number of transmitted neutrons; go to 5
- 4 repeat step 1 - 3 until final result is achieved for all neutrons
- 5 repeat step 1 - 4 with more incident neutrons

