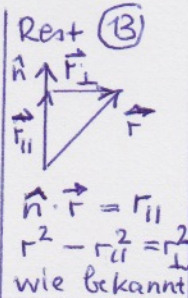


① $\nabla \Phi = \frac{\partial \Phi}{\partial \mathbf{r}} \hat{\mathbf{n}}$

$\nabla \frac{1}{r} = \frac{\partial(1/r)}{\partial r} \hat{\mathbf{r}} = -\frac{1}{r^2} \hat{\mathbf{r}}$

$\nabla z = \frac{\partial z}{\partial z} \hat{\mathbf{z}} = \hat{\mathbf{z}}$



② $z_0 \downarrow \downarrow g$ $ma = \frac{z}{L} mg$
 gesamte Masse wird beschleunigt g wirkt nur auf überläng. Stück

$\ddot{z} = \frac{z}{L} g$ Ansatz $z = z_0 e^{\alpha t}$
 $\alpha^2 z = z \frac{g}{L}$, $\alpha = \sqrt{\frac{g}{L}}$, $z = z_0 e^{t\sqrt{g/L}}$

③ $\vec{r} \times \dot{\vec{r}} = \text{const}$, davon z-Komponente
 $x\dot{y} - y\dot{x} = \text{const}$

④ Reine Längen-
 änderung nur
 möglich für Bewegung
 der Massen entlang
 Diagonale!

$\begin{cases} m\ddot{x} = -k_1 x + k_2 \cdot 0 \\ m\ddot{y} = k_1 \cdot 0 - k_2 y \end{cases} \Rightarrow \ddot{\vec{r}} = -\frac{k}{m} \vec{r}$
 $\rightarrow \omega = \sqrt{\frac{k}{m}}$

⑤ 2π inverse Trafo ist bei Drehung $\varphi \rightarrow -\varphi$

$\begin{cases} x = x'c - y's \\ y = x's + y'c \\ z = z' \end{cases}$ mit $s = \sin\varphi, c = \cos\varphi$
 $\begin{cases} \dot{x} = \dot{x}'c - \dot{y}'s - x'\omega s - y'\omega c \\ \dot{y} = \dot{x}'s + \dot{y}'c + x'\omega c - y'\omega s \end{cases}$

$\dot{x}^2 + \dot{y}^2 + \dot{z}^2 = \dot{x}'^2 c^2 + \dot{y}'^2 s^2 + x'^2 \omega^2 s^2 + y'^2 \omega^2 c^2 + \dot{x}'^2 s^2 + \dot{y}'^2 c^2 + x'^2 \omega^2 c^2 + y'^2 \omega^2 s^2 + 0 + 0 - \dot{x}'y'\omega c^2 + 0 + \dot{y}'x'\omega s^2 - \dot{x}'y'\omega s^2 + \dot{y}'x'\omega c^2 + \dot{z}^2$, also

$L = \frac{1}{2} m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) = \frac{1}{2} m[(\dot{x}'^2 + \dot{y}'^2 + \dot{z}'^2) + \omega^2(x'^2 + y'^2) + \omega(x'y' - x'y')]$

⑥ $\frac{d^2 f}{dx^2} \Big|_i = \frac{d}{dx} f' \Big|_i$
 $= \frac{f'_{i+1/2} - f'_{i-1/2}}{dx} = \frac{f_{i+1} - f_{i-1}}{dx} - \frac{f_i - f_{i-1}}{dx} = \frac{f_{i+1} - 2f_i + f_{i-1}}{dx^2}$

$\sum_{i-1}^{i+1} m \ddot{\xi}_i = -k(\xi_i - \xi_{i-1}) + k(\xi_{i+1} - \xi_i)$

$m \ddot{\xi}_i = k(\xi_{i+1} - 2\xi_i + \xi_{i-1}) = k \xi_i'' dx^2$

$m \left(\frac{d^2}{dt^2} - \frac{k}{m} dx^2 \frac{d^2}{dx^2} \right) \xi_i = 0$

$\left(\frac{d^2}{dt^2} - \omega^2 dx^2 \frac{d^2}{dx^2} \right) \xi_i = 0$

$\left(\frac{d^2}{dt^2} - a^2 \frac{d^2}{dx^2} \right) \xi(x,t) = 0$

⑦ $0 = \delta S = \delta \int \sqrt{dx^2 + dy^2} = \delta \int dx \sqrt{1+y'^2}$

E-L: $0 = \frac{d}{dx} \frac{\partial \sqrt{1+y'^2}}{\partial y'} - \frac{\partial \sqrt{1+y'^2}}{\partial y}$
 $0 = \frac{d}{dx} \frac{y'}{\sqrt{1+y'^2}} = \frac{\sqrt{1+y'^2} y'' - y' \frac{2y'y''}{2\sqrt{1+y'^2}}}{1+y'^2}$

$= \frac{(1+y'^2) y'' - y'^2 y''}{1+y'^2} = \frac{y''}{1+y'^2}$

d.h. $y'' = 0 \rightarrow y = ax + b$, Gerade

⑧ $z = z_0 + \frac{p_0}{m} t + \frac{1}{2} g t^2$

$p = p_0 + mgt$

$\rightarrow z_0 = z - \frac{p_0}{m} t - \frac{1}{2} g t^2$

$= z - \left(\frac{p - mgt}{m} \right) t - \frac{1}{2} g t^2$

$z_0 = z - \frac{p}{m} t + \frac{1}{2} g t^2 = z_0(z, p)$

$p_0 = p - mgt = p_0(z, p)$

$\{z_0, p_0\}_{z, p} = \frac{\partial z_0}{\partial z} \frac{\partial p_0}{\partial p} - \frac{\partial z_0}{\partial p} \frac{\partial p_0}{\partial z}$

$= 1 \cdot 1 - \frac{t}{m} \cdot 0 = 1$. d.h. $(z_0, p_0) \rightarrow (z, p)$

ist eine kanon. Trafo, weil (z_0, p_0) und (z, p) kanon. Variable sind. d.h. zeitliche Entwicklung ist eine kanon. Transf.

⑨ $\frac{dV}{dt} = -\frac{d}{dt} \int dx dy dz = \oint dx dy \omega + \oint dx dz \nu + \oint dy dz u$

 $dx = u dt$

⑩ $D_{x,t} G(x,t, x', t') = \delta(x-x') \delta(t-t')$

$\Psi(x,t) = \int dx' \int dt' G(x,t, x', t') f(x', t')$

⑪ Vorlesung! ⑫ $\Theta = (\Theta_{ij})$ mit Trägheitsmoment Θ_{ij}
 ⑬ $\Theta = \hat{\mathbf{n}}^T \cdot \Theta \cdot \hat{\mathbf{n}} = \hat{\mathbf{n}}^T \cdot \left(\int dV (r^2 \mathbb{1} - \vec{r} \vec{r}) \right) \cdot \hat{\mathbf{n}} = r^2 - (\hat{\mathbf{n}} \cdot \vec{r})^2$